Using System Dynamics for Automated Vehicle Impact Assessment

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Disclaimer

Statements made during this presentation are opinions of the speaker and do not represent official positions of the U.S. Department of Transportation.



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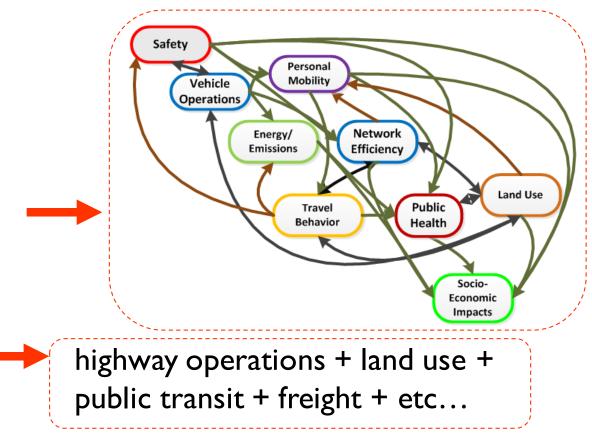
AV impacts are complex

The problem: assessing impacts will not be easy, and the stakes may be high.

- There will be far reaching impacts across many areas, and across multiple time-frames
- Multiple highly complex systems are involved (complex interactions both **within** and **among** these systems)



- Technology performance
- Policy response 0
- Human behavior
- New business models

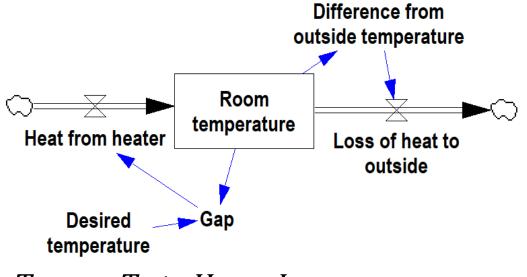


- Will the technology perform as expected?
- What could drive policy responses, and will those responses be effective/timely?
 - How will individuals/families use automated vehicles?
 - How will businesses use automated vehicles?
- (note: even more uncertainty emerges when cooperation among vehicles—cooperative driving automation—is considered) 0



System dynamics

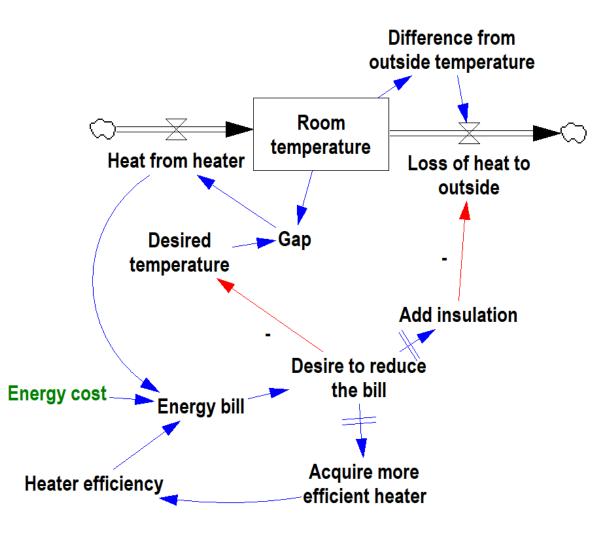
Applies ideas from control systems theory to complex technological, social and economic problems.



$$T_{i+1} = T_i + H_i - L_i$$

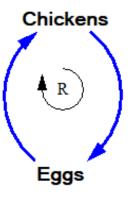
$$H_i$$
 = positive constant, if Desired temp. > Room temp.
0 otherwise

See https://systemdynamics.org/what-is-system-dynamics/





Basic constructs in system dynamics



Reinforcing Loop

- Exponential growth or decline
- "Going viral"
 - New product taking over a market as more people learn about it
 - Epidemic

Balancing Loop

- Reaches an equilibrium, perhaps with oscillation
- Examples
 - Congestion on a road
 - Limits on food in an ecosystem

Stock and Flow



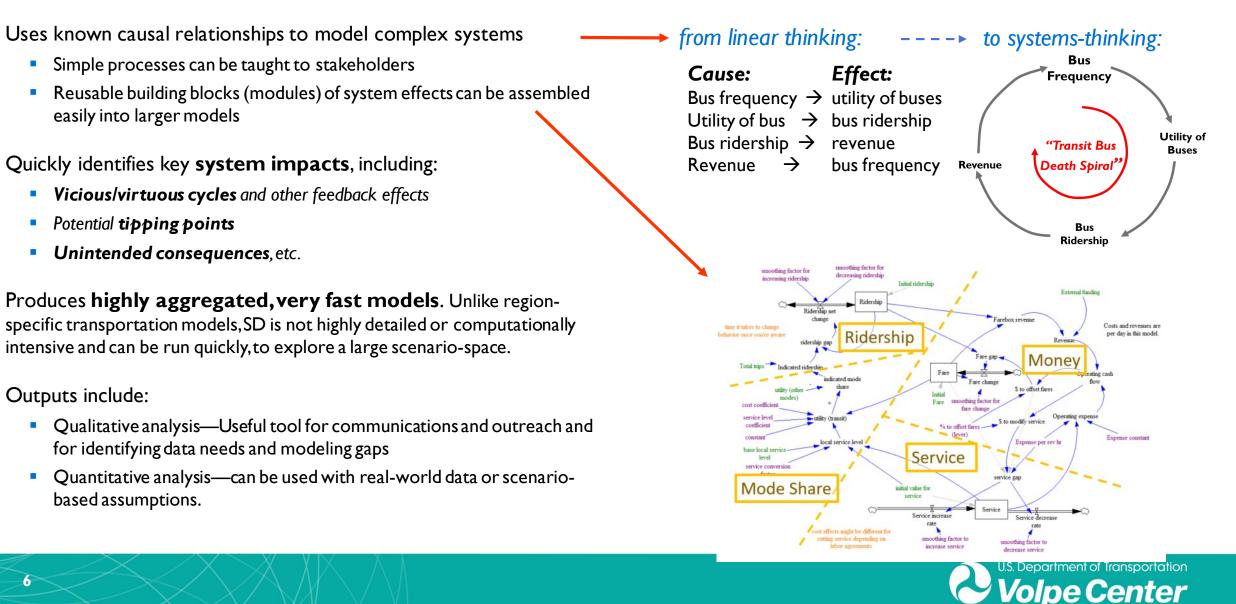
- Stock = accumulation of something
- Flow = change in the accumulation
- Examples
 - Firm's cash on hand
 - Fleet size
 - Persons familiar with automated vehicles
 - OEM technical knowledge
 - Refueling infrastructure
 - Population in a region



of transit B Transit ridership Crowding

Attractiveness

System dynamics (SD) is a higher-level strategic modeling tool



Building blocks for SD transportation models

- Technology adoption: Consumer adoption of a new product, via word-of-mouth and other influencing factors
- 2. Business models: Business provision of a service, relying on the availability of factors of production, how customers pay, and profitability
- 3. Competition: What mode does the traveler choose?





Building blocks for SD transportation models

- 4. Reinforcing effects of services and users, where greater usage of a service justifies adding more service and/or higher quality service
- 5. Balancing effects of use: Congestion effects, where as something is used more (e.g., road space), its use becomes less desirable
- 6. Long term dynamics
 - Vehicle ownership
 - Land use (residential relocation)

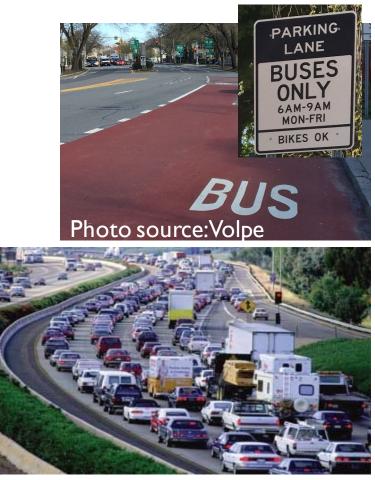
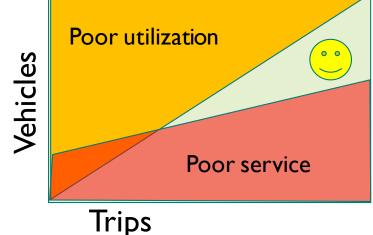


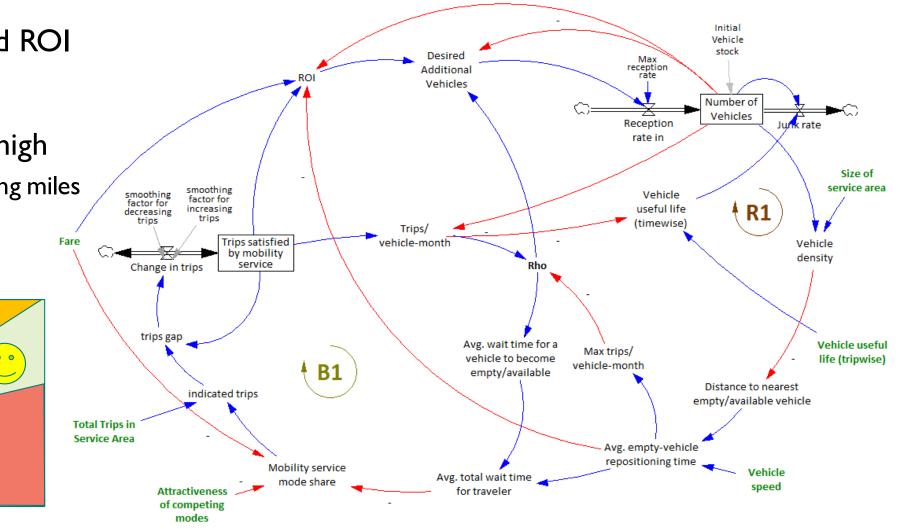
Photo source: FHWA



Short term dynamics: a shared vehicle service

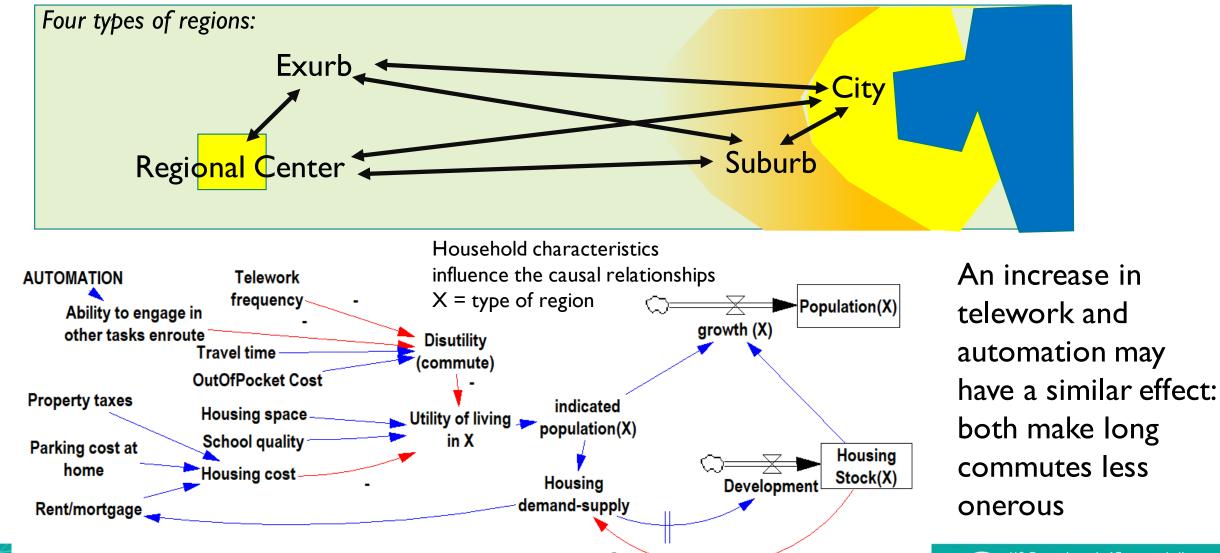
- Too many vehicles?
 - Poor utilization and ROI
- Too few vehicles?
 - Poor service with high
 - empty repositioning miles
 - \circ traveler wait time







Long term dynamics: land use





Outcomes to date: SD has been a powerful communications and engagement tool

- I. Helped planners and modelers "speak the same language" regarding complex changes to transit demand and land use
- 2. Provides a way to structure collaborations with stakeholders from multiple disciplines
- 3. It can be a useful strategic tool for rapid analysis of any complex system, especially hard-to-quantify socio-technical systems
- 4. Can complement other strategic tools, such as VisionEval
- 5. Can be applied at various levels
 - Communications and engagement tool
 - Structuring thinking with your team, clients and stakeholders—enabling a "systemsthinking" approach
 - Rigorously modeling causal relationships
 - Quantitative models



For more information

- Transport Research Arena conference paper from a 2019 workshop in Leeds, UK: Rakoff et al, Building Feedback into Modelling Impacts of Automated Vehicles: Developing a Consensus Model and Quantitative Tool (April 2020) <u>https://rosap.ntl.bts.gov/view/dot/48969</u>
- Webinar, sponsored by the Zephyr Transport Foundation, that included a group model building exercise on road safety: A System Dynamics Perspective for Transportation Planning Under Uncertainty (May 2020) Slides and recording: <u>https://zephyrtransport.org/events/2020-may-learning-system-dynamics/</u>
- Report that includes modeling of the proxy modes of ridehailing (user response) and dockless bike share (vehicle utilization): Berg, Ian, Hannah Rakoff, Jingsi Shaw and Scott Smith: System Dynamics Perspective for Automated Vehicle Impact Assessment, (FHWA-JPO-20-809) (July 2020) <u>https://rosap.ntl.bts.gov/view/dot/49813</u>
- Report from our work with transport planning organizations in the U.S. to apply system dynamics to planning, with a focus on transit: Automated Vehicle Impacts on the Transportation System: Using system dynamics to assess regional impacts (March 2021) <u>https://rosap.ntl.bts.gov/view/dot/55247/</u>
- Webinar, sponsored by the Zephyr Transport Foundation, that summarized our work with transport planning organizations in the U.S.: System dynamics for strategic planning under technological uncertainty (April 2021) <u>https://zephyrtransport.org/events/2021-04-21-system-dynamics-applications/</u>
- Presentation from the 18th TRB Planning Applications Conference. Rakoff, Hannah, Alex Bettinardi: Testing a system dynamics approach for modeling mode shift and equity under uncertainty (June 2021)

