

FOTs in the Tokyo Waterfront area FY2019 to 2020 Results and Overview of Implementation in FY2021

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- 1. History of the FOTs in the Tokyo Waterfront Area
- 2. FY2019 to 2020 Results
- 3. Overview of Implementation in FY2021
- 4. FY2021 traffic signal prediction information transmission test

1. History of the FOTs in the Tokyo Waterfront Area

- In preparation for the expansion of ODDs for advanced driving assistance and automated driving, research and testing results have been steadily
 produced. This includes the establishment of static information infrastructure (FY2017-2018) and the evaluation of the effectiveness of dynamic
 information (FY2019-2020).
- In FY2021, the project will envision the traffic environmental information that will be essential in the future and construct a system of utilizing dynamic information in order to realize advanced, cooperative drive assistance and automated driving by providing information over wide areas using public networks (V2N)



1. History of the FOTs in the Tokyo Waterfront Area



2. FY2019 to 2020 Results

(1) FY2019-2020 issues, verification items, and objectives

Today's explanation

Region	Test contents	Issue	Verification item	Objective
Water front City	Infrastructure information utilization in intersections with traffic signals	 Ensure reliability of signal recognition Avoid disturbing traffic flow in dilemma zones 	 Traffic signal information effectiveness and conditions (a) Effectiveness of traffic signal color information (b) Effectiveness of traffic signal remaining seconds information (2) Assess impact of autonomous vehicle driving on traffic flow and the factors involved 	 Verify effectiveness of traffic signal information distribution Reach consensus with test participants regarding standardized specifications Identify traffic signal information distribution conditions Clarify issues to be addressed in order to cultivate a sense of acceptability in society
Express ways	ETC gate passing/merging support information distribution	 Smooth toll booth gate passing Support for merging with cruising lines based on actual cruising line vehicle speeds 	 (1) Confirm the effectiveness of ETC gate passing support information (2) Confirm the effectiveness of merging support information 	 Develop infrastructure information provision specifications Determine infrastructure installation conditions Clarify issues in order to define specifications based on FOTs Identify infrastructure needs and prioritization requirements
Haneda Airport	Environmental conditions for practical implementation of level 4 ART	 Clarify environmental conditions required for practical implementation of level 4 ART in mixed transportation environments 	 Analyze factors necessitating driver involvement in mixed transportation environments Effectiveness of cooperative infrastructure in regularly scheduled transport Comfort when boarding/exiting Assess impact of autonomous vehicle driving on traffic flow, and factors causing this impact 	 Clarify which infrastructure is required for the expansion of ODD Identify what infrastructure conditions are required for the improvement of ART service Clarify issues to be addressed in order to cultivate a sense of acceptability in society

(2) Contents of FOTs in the Waterfront City area and FOTs area

1) Verification contents

Transmitting traffic signal information by wireless ITS devices to **implement advanced automated driving on general roads**



SIP

2) FOTs area



(a) Waterfront City area



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(3) Waterfront City area FOTs results: Infrastructure information utilization in intersections with traffic signals - effectiveness and conditions

(a) Effectiveness of traffic signal color information [factors that interfere with traffic signal color recognition*1]

Backlighting



It is difficult to determine the traffic signal color due to light sources such as the sun, the headlights of oncoming vehicles, or reflections from buildings



Direct lighting

It is difficult to identify traffic signal colors due to light sources such as the sun

Raindrops





The view of the traffic signal is obstructed by large nearby vehicles, vegetation, elevated road sections, or other structural elements

Blending into background * From materials prepared by the Kanazawa University Promotion Committee While the color of a traffic signal

can itself be determined. the outline, etc. of the traffic signal blends in with the building behind it or other background elements. reducing the reliability of traffic signal detection.

Nighttime



At night, there are light sources such as street lamps and building lights that make traffic signal color recognition difficult



Raindrops cling to the camera, making it difficult to identify traffic signal colors

*1 Identified based on test participant driving data and feedback regarding it

- *2 This refers to situations in which there are obstructions, such as preceding vehicles or nearby structures, between a test vehicle and a traffic signal, preventing the vehicle's on-board camera from being able to identify the traffic signal color (This includes curves, grades, and other road structures)
- The evaluation of the effectiveness of traffic signal color information was performed using driving data for all intersections
- Information regarding conditions when interference factors occurred were collected from all Waterfront City area intersections on a per-factor basis 6

(3) Waterfront City area FOTs results: Infrastructure information utilization in intersections with traffic signals - effectiveness and conditions

(b) Effectiveness of traffic signal color information [Examples of concealment/obstruction]

The traffic signal color could not be recognized until four seconds after the traffic signal turned green





Experiment date/time	Automated driving	Intersection no.	Name of intersection	Conditions
2020/10/26 16:33	-	В	Telecom Station-mae	Concealment/ obstruction

	Entry route	Exit route	Traffic signal color	Duration of period when traffic signal color could not be recognized
2	Route 2	Route 1	$\text{Red} \rightarrow \text{Green}$	4 seconds



All drivable lane node linkages are connected in the data

(4) Guidelines on the creation of dynamic maps and high-accuracy 3D map data figh-accuracy 3D map data

本ガイドラインは、「戦略的イノペーション創造プログラム(SIP)第2類/ 自動運転(システムとサービスの転張)/東京職品部実証実験の実施」を通 して明らわらなった、「自動走行システム向け地図データ仕様への提案 Ver.11」(以下、「SIP 地図データ仕様」とする)における地図データ件成者 の解釈によって地図データ作成基準にばらつきが生じる可能性のある既体な 記述に対すら留置事項を取りまとめたものである。なお、本ガイドライン は、「SIP 地図データ仕様」の記述を変更することなく、補足説明を追犯した ものとなっているため、本ガイドライン1日帯でSIP 地図データ仕様に到った 地図データの作成が行える構実となっている。また、本ガイドラインは協聞 領域の地図データを作成するための一動となることを目的にまとめたもので あり、「SIP 地図データ仕様」及びその割集元である「高度 DRM-DB 資料」 の修正や変更を求めるものではない。

※「自動走行システム向け地図データ仕様への機業 Ver.1.1」: 内閣合が実施する「「戦略的イノベーション制造フログラム (SIP)・自動 た行システム」(内10)、自動在行システムの双環に向けた課題程とその 解決の方向性に関する調査・検討におけるダイナミックマップ構築に向け た駅下・評価に係る調査検討」の受託者であるダイナミックマップ構築に向け た駅下・評価に係る調査検討」の受託者であるダイナミックマップ構築に 約コンソーシアムが、平成29 44℃一般対信法人日本デジタル道路相較協 会が数量した実度デジタル道路情報が応続計会において検討した先進運転 支援のための新しい高度デジタル道路情報に関する資料(「高度 DRM-DB 資料」)を翻案した二次著作物。

> 令和3年3月 東京臨海部実証実験コンソーシアム







(1) Overview, implementation items, and objectives

Overview of initiatives

 Create a wide area information distribution system envisioned for social deployment and perform FOTs in actual roadway traffic environments with the aim of expanding the Operational Design Domain (ODD) of mobility and logistics services using advanced drive assistance, autonomous vehicles, and automated driving technologies by providing dynamic information via infrastructure (vehicle-infrastructure cooperation)

FY2021 implementation items

Deliver traffic environmental information via V2N and confirm the information's effectiveness and specifications

- Traffic signal prediction information
- Lane-specific roadway traffic environmental information

- · Simulated emergency vehicle location information
- Rainfall information

FY2021 objectives

- Verify use of cooperative systems in tackling challenges involved in implementing advanced automated driving
 - > Verify the effectiveness of different traffic environmental information used in the FOTs
 - > Confirm standardization specifications and reach consensus by test participants
 - > Issue recommendations for the test equipment (infrastructure) used in these FOTs
 - > Clarify issues to be addressed in order to cultivate a sense of acceptability in society
 - > Share results with related organizations (JAMA, etc.)

(2) Evaluation approach and structure of test system



(3) The data and communication media of the FOT



Data	Data: detail	Media
(1)Dynamic	Traffic signal information	V2I:Advanced infrared beacon & ITS RSU(760MHz)
	Traffic signal prediction information	V2N:LTE
	Simulated emergency vehicle location information	V2N:LTE
(2)Semi-dynamic	Lane-specific roadway traffic environmental information	V2N:LTE
	Rainfall information(wide area)	V2N:LTE
(3)Semi-static	Rainfall information(narrow area)	V2N:LTE
(4)Static	Map data	Cloud Server
	Updated data	Cloud Server

(4) Static data : Features of high-accuracy 3D map

- * Road shoulder
- * Center line
- * Lane line
- * Lane edge

- * Stop line
- * Pedestrian crossing
- * Road marking
- * Traffic signal
- * Road sign

- * Carriageway link
- * Lane link
- * Intersection lane link
- * Area-formed intersection
- * CRP node

(4) FOTs area

• The wide-area dynamic map created in SIP Phase 1 and the same map updated with the latest data during SIP Phase 2 will be used





(5) Delivered information, issues, verification items, and objectives

Delivered information	Issue	Verification item	Objective
Traffic signal prediction information (V2N)	 Confirm achievement of reliable signal recognition Confirm usage methods and effectiveness of information delivered via V2N communications (planned) 	 Confirm operations used to deliver traffic signal prediction information Collect traffic signal information through actual driving (V2I, V2N) Propose effective methods of utilizing traffic signal prediction information, including in applications other than vehicle control as well 	 Confirm effectiveness of traffic signal prediction information delivery (V2N) (clarify at which intersections the information can be effectively delivered via V2I/V2N, limiting conditions, etc.) Confirm the specifications of traffic signal prediction information (V2N). Summarize participant consensus, requests, etc.
Lane-specific road traffic information (Caution information)	• There are restrictions on driving using vehicle- mounted sensors alone and limits to the distance at which vehicle-mounted sensors can detect obstacles, so infrastructure look-ahead information must also be provided	 Verify system used to supply lane-specific road traffic information (caution information) Verify improvements in accuracy due to increase of number of samples of probe information compared to FY2020 Confirm accuracy of information through driving in actual traffic environments (confirm effectiveness in path planning) 	 Verify effectiveness of delivery of lane-specific road traffic information (caution information) (clarify limiting conditions) Prepare lane-specific road traffic information (caution information), confirm delivery specifications, and obtain consensus of participants
(Mock) Emergency vehicle location information	 Appropriate response when an emergency vehicle approaches during automated driving* (stopping, pulling off onto the shoulder, etc.) 	 Verify system used to provide emergency vehicle location information Confirm accuracy of information in actual driving environments (actual position of mock emergency vehicle, comparison versus received information, etc.) Reflect findings in specifications based on deliberations regarding vehicle behavior taken in response to mock emergency vehicle location information 	 Confirm effectiveness of delivery of emergency vehicle location information (clarify the limiting conditions that apply to the use of emergency vehicle location information) Prepare emergency vehicle location information, confirm delivery specifications, and obtain consensus of participants

(5) Delivered information, issues, verification items, and objectives

Delivered information	Issue	Verification item	Objective
Rainfall information	 Make decisions regarding automated driving during poor weather and issue TORs sufficiently in advance 	 Confirm operations used to deliver rainfall information Reflect findings in specifications based on investigation of vehicle behavior taken in response to provision of rainfall information within provision scope *TOR: Take Over Request 	 Verify effectiveness of rainfall information delivery format and weather prediction information (clarify limiting conditions) Prepare rainfall information, confirm delivery specifications, and obtain consensus of participants

(6) FY2021 FOTs Schedule

	Information loca	n provision Ition		20	21	2022			
Item	Waterfront City	Express- ways	Sep	Oct	Nov	Dec	Jan	Feb	Mar
Milestone					SI	I P-adus WS:	l Nov. 9, 10		
 FOTs (V2N) 1) Rainfall information 2) Lane-specific traffic environmental information 3) Traffic signal prediction information 4) Simulated emergency vehicle location information 	0 - 0 0	00-							

4. FY2021 traffic signal prediction information transmission test

(1) Intersections within traffic signal prediction information delivery scope

Preparation of scope of intersections involved in the Waterfront City area FOTs "Confirmed information" "Information with margins" "No traffic signal current status/remaining seconds"



The test will be performed for 30 intersections that provide confirmed information and information with margins

Provided

本明 コロシアム東	
車明コロシアム北	_
●「明コロシアノ西●有明中央橋北	_
有明中央橋南	
有明テニスの森	
	_
有明二丁目北 東京ビッグサイト前 ー	
	_
▲海浜22園入口 東京ビッグサイト正門	_
△場一丁目 有明橋西 ▲フナリー 入頭入口	
	_
ロ場前前16(米間) 28音場中央第二(角側) 東京湾岸アンダー出口	
「潮風公園北	_
「編風公園南」 「「「」 Intersections that provide confirmed information	_
▲ Intersections that provide information with margins	_
船の科学館入口	_
	_
東京湾岸警察者前 ーーデレフトセンター前	
東京港湾合同庁舎前	-
テレゴム駅前	-

ID	Name of intersection	information	ID	Name of intersection	information
2	Telecom Station-mae	Confirmed	107	Daiba 1-chome	Confirmed
80	Tokyo Wangan Police	Confirmed	108	Kaihin Park Entrance	Margin
09	Station-mae	Commed	109	Ariakebashi West	Confirmed
91	Ariake Coliseum East	Margin	110	Rainbow Entrance	Margin
92	Ariake Station-mae	Margin			Remaining
95	Shiokaze Park North	Margin	111	Tokyo Wangan Underpass	seconds
96	Shiokaze Park South	Margin		Exit	available
97	Museum of Maritime Science	Margin	112	Ariake Tennis-no-mori Park	Confirmed
	Entrance		113	Ariake 2-chome North	Margin
Takyo Port Bay Godo choch		Remaining	114	Ariake 2-chome South	Margin
98	Bldg-mae	information not	115	Ariake 3-chome	Confirmed
	2.09	available	116	Ferry Terminal Entrance	Margin
99	DaibaEkimae No. 2 (East)	Margin			Remaining
100	DaibaEkimae No. 1 (West)	Margin	117	Ariake Coliseum West	seconds
101	Aomi 1-chome West	Confirmed			information not available
102	Daiba	Confirmed		Tokyo Big Sight Front	available
103	Central Odaiba No. 1 (North)	Confirmed	118	Entrance	Margin
104	Central Odaiba No. 2 (South)	Confirmed	119	Ariake Coliseum North	Confirmed
105	Teleport Ekimae	Confirmed	120	Ariake Chuobashi North	Margin
106	Telecom Center-mae	Confirmed	121	Ariake Chuobashi South	Margin
			131	Aomi 1-chome	Margin
			132	Tokyo Big Sight-mae	Margin

Drovidod

4. FY2021 traffic signal prediction information transmission test

(2) Conceptual image of changes to intersections for which information is delivered by PUSH delivery (specified intersection) based on vehicle position

Information is output for the maximum number of intersections for which information can be acquired (in this example, three intersections), starting from the first intersection on the traversed intersection list, excluding intersections that have already been traversed

Note) The number of intersections setting can be changed Output all 30 intersections - output minimum of 1 intersection : Can be used to test load, processing capabilities, etc.



Traffic signal prediction information acquisition/output intersection matrix

Sel	Timing of info acquisition intersection switching ected intersection) Start driving) Traverse Telecom Station) Traverse Telecom Center-mae) Traverse Aomi 1-chome) Traverse Teleport Ekimae) Traverse Central Odaiba No. 2 (South)) Traverse Central Odaiba No. 1 (North)) Traverse Daiba) Traverse Daiba 1-chome	0) Traverse Kaihin Park Entrance
1	Telecom Station-mae	0		X	×	×	×	×	×	X	×
2	Telecom Center-mae	0	0		×	×	×	×	×	×	×
3		0	0			\mathbf{v}	\sim	~	~	~	×
	Aomi 1-chome	0	0			\sim	\sim	\sim	~		\sim
4	Aomi 1-chome Teleport Ekimae		0	0	0		×	×	×	×	×
4 5	Aomi 1-chome Teleport Ekimae Central Odaiba No. 2 (South)	×	0	000	0		< ×	× × ×	× × ×	× × ×	× × ×
4 5 6	Aomi 1-chome Teleport Ekimae Central Odaiba No. 2 (South) Central Odaiba No. 1 (North)	× ×	0 0 ×	000	000		× × O	< × ×	× × × ×	× × × ×	× × × ×
4 5 6 7	Aomi 1-chome Teleport Ekimae Central Odaiba No. 2 (South) Central Odaiba No. 1 (North) Daiba	× × ×	0 0 × ×	0 0 ×			0 0 × ×	< × × 0	× × × ×	× × × × ×	× × × × ×
4 5 6 7 8	Aomi 1-chome Teleport Ekimae Central Odaiba No. 2 (South) Central Odaiba No. 1 (North) Daiba Daiba 1-chome	× × × ×					< × 0 0 0	< × × 0 0	× × × × O	< × × × × ×	× × × × ×
4 5 6 7 8 9	Aomi 1-chome Teleport Ekimae Central Odaiba No. 2 (South) Central Odaiba No. 1 (North) Daiba Daiba 1-chome Kaihin Park Entrance							 × × 0 0 0 	× × × × × 0 0	× × × × × × 0	<
4 5 6 7 8 9 Unse	Aomi 1-chome Teleport Ekimae Central Odaiba No. 2 (South) Central Odaiba No. 1 (North) Daiba Daiba 1-chome Kaihin Park Entrance elected intersection	× × × × × × ×		0 0 0 × × × × ×	× × × 0 0 0 × ×		× × 0 0 0 ×	× × × 0 0 0 ×	× × × × × 0 0 ×	* * * * * * * * * * * * * * * * * * *	* × * × * × * × * ×

 Intersection for which traffic signal prediction information is acquired/output

X : Intersection for which traffic signal prediction information is not acquired/output 16

4. FY2021 traffic signal prediction information transmission test

(3) Conceptual image of delivery of traffic signal prediction information using PUSH delivery (specified intersection)

Conceptual image of traffic signal prediction information graph



Thank you