Challenge to establish ecosystem of sustainable mobility -Academic collaboration and practice-

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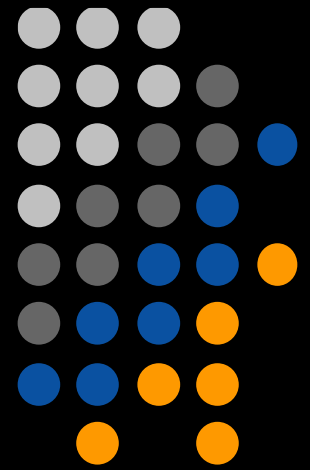

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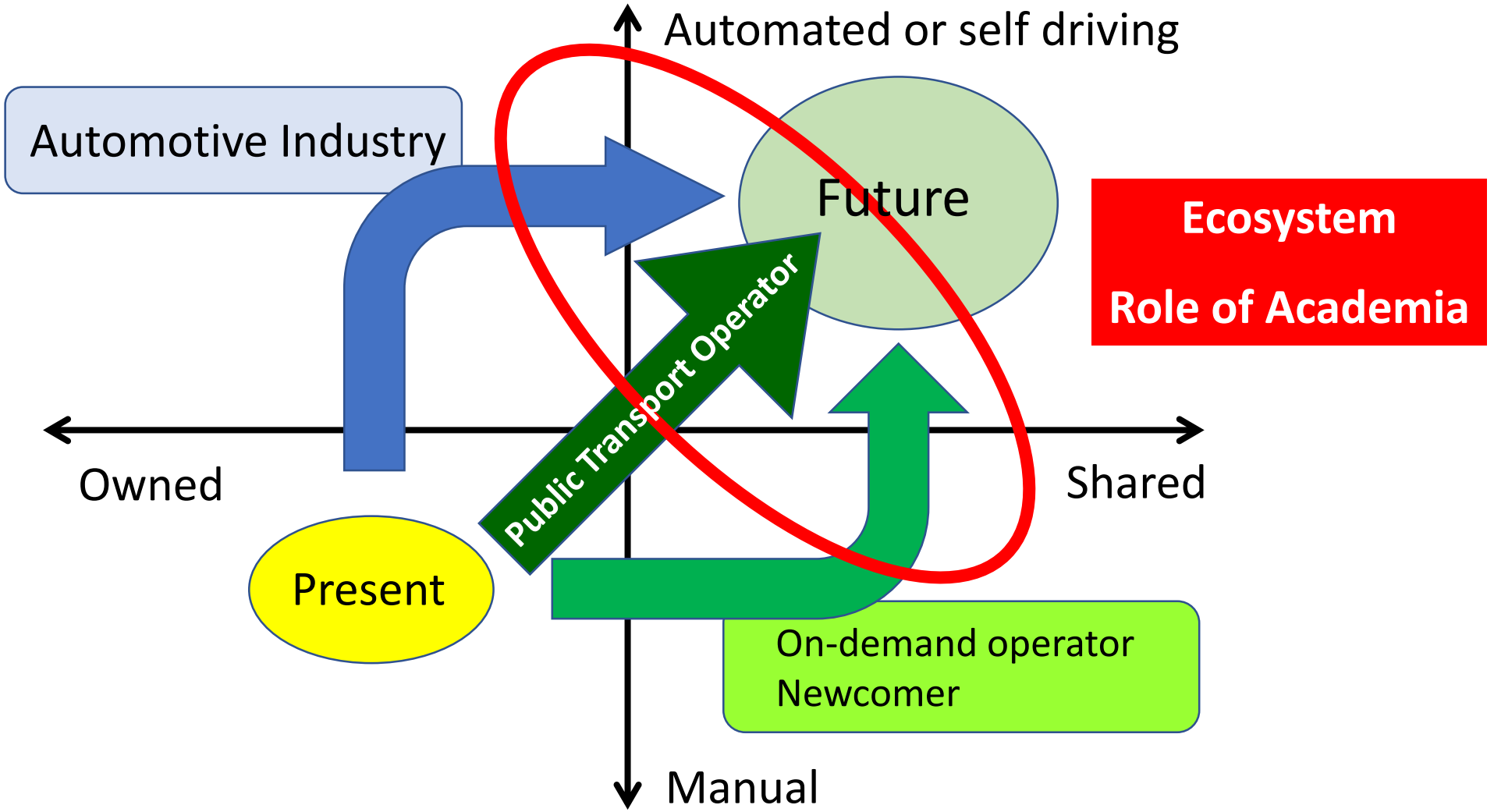
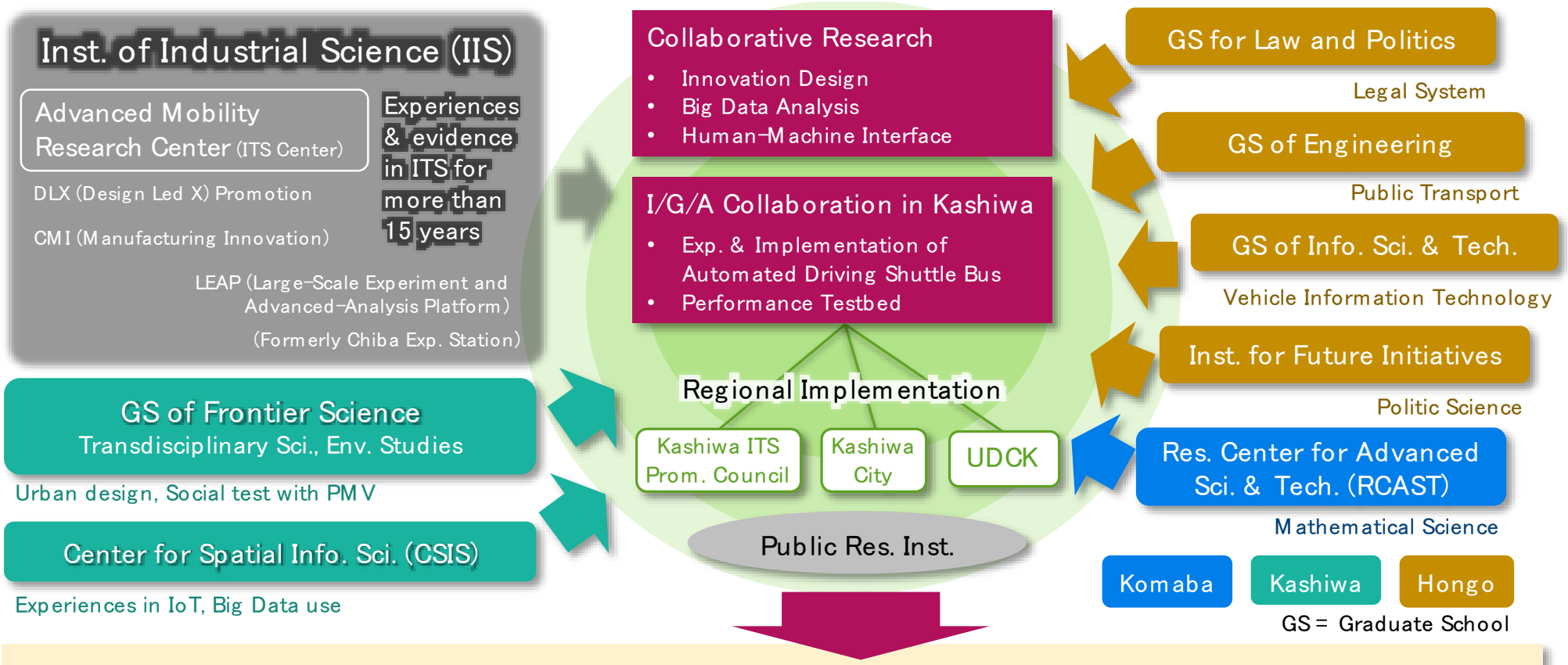
Mobility as a Service and social change



Mobility Innovation Collaborative Research Organization (UTmobI), The University of Tokyo



- Intra/International Promotion of mobility innovation based on the experience at Kashiwa-area using the academic promotion council.
- Nurturing Young Persons & Social Return Activity for promoting mobility innovation (Ideathon, Hackathon)

Academic research model collaborated with real society beyond simple social return activity

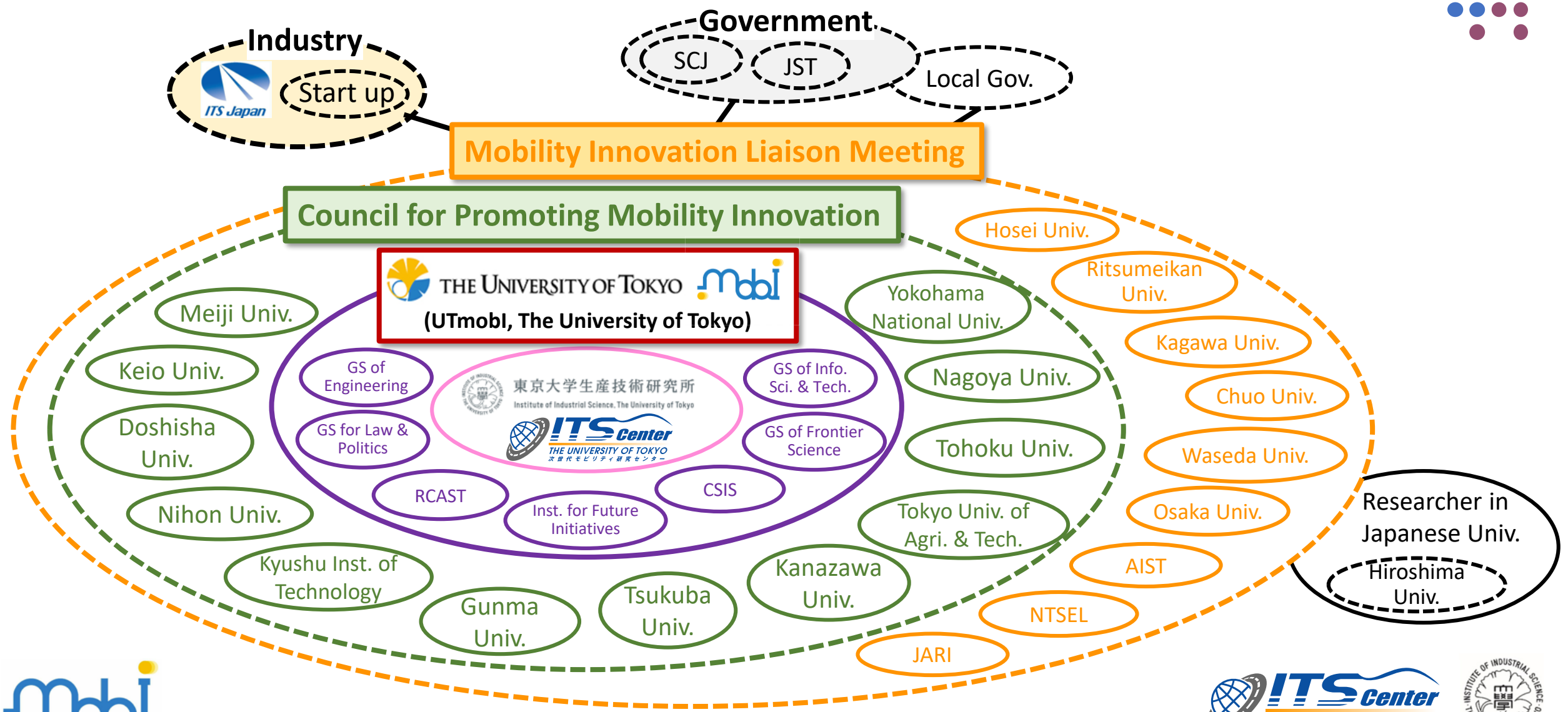
Systematic knowledge to innovate mobility and promotion for regional implementation

ITS R&R Experiment Fields
(Large-Scale Experiment and Advanced-Analysis Platform (LEAP), IIS)

Utilization by venture company of automated driving technologies (Kashiwa Open Campus 2019, The Univ. of Tokyo)

Sustainable Mobility* Framework organization by exploiting automated driving technologies

* Tentative



Consortium to realize Level 4 Mobility Services

ITS Japan Collaboration mobi

Local Gov.
Otsu City,
Futaba Town, etc.
Local ITS group

Cabinet Secretariat
MIC Ministry of Internal Affairs and Communications
Cabinet Office
METI Ministry of Economy, Trade and Industry
NPA National Police Agency
MLIT Ministry of Land, Infrastructure, Transport and Tourism

AIST
dARI 日本自動車研究所
NILIM

ITS AMERICA
ERTICO ITS EUROPE
ITS

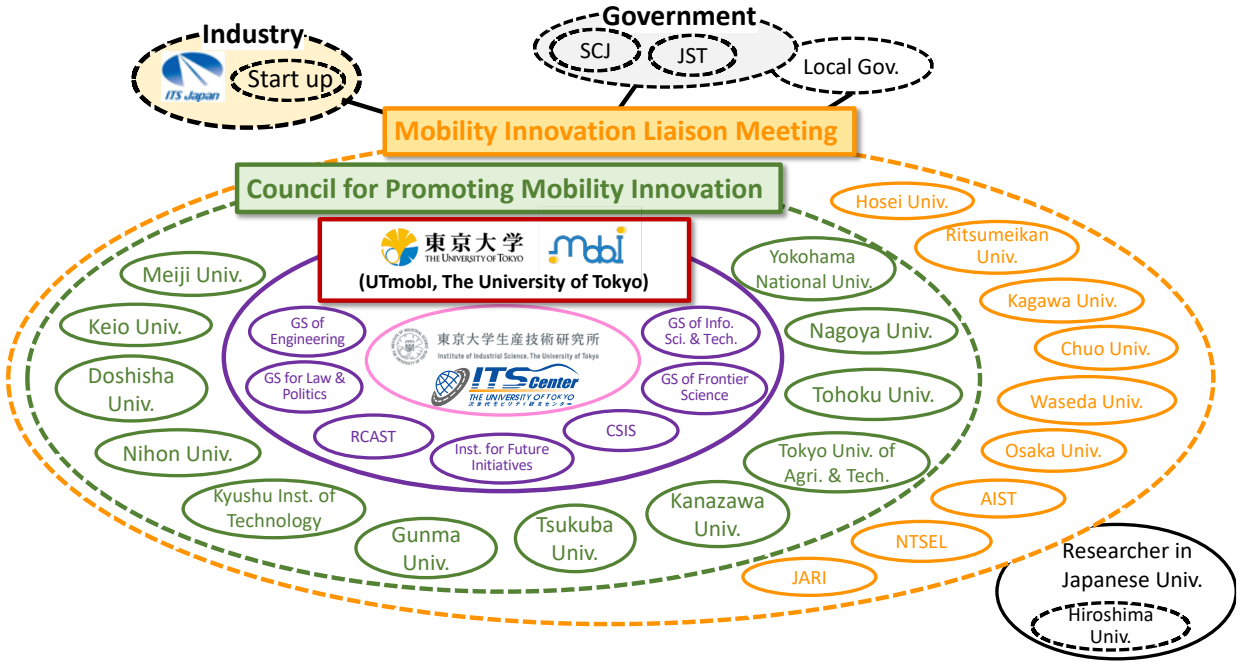
ITS Japan

Automated Driving Research Activity

TOSHIBA
BOLDLY UPDATE MOBILITY
JRC Mobility
TOHOKU UNIVERSITY CREATING GLOBAL EXCELLENCE
OMRON オムロンソーシアルソリューションズ株式会社
JTEKT 株式会社ジェイテクト
PASCO
NIPPON PAINT INDUSTRIAL COATINGS CO.,LTD.
Kitami Institute of Technology
THE UNIVERSITY OF TOKYO
HIDO 一般財団法人 道路新産業開発機構 Highway Industry Development Organization
MITSUBISHI ELECTRIC Changes for the Better 三菱電機
JARTIC 日本道路交通情報センター
Tokio Marine & Nichido Fire Insurance Co.,Ltd.
scheme verge

Integrated Mobility Service Project

Project based Committee



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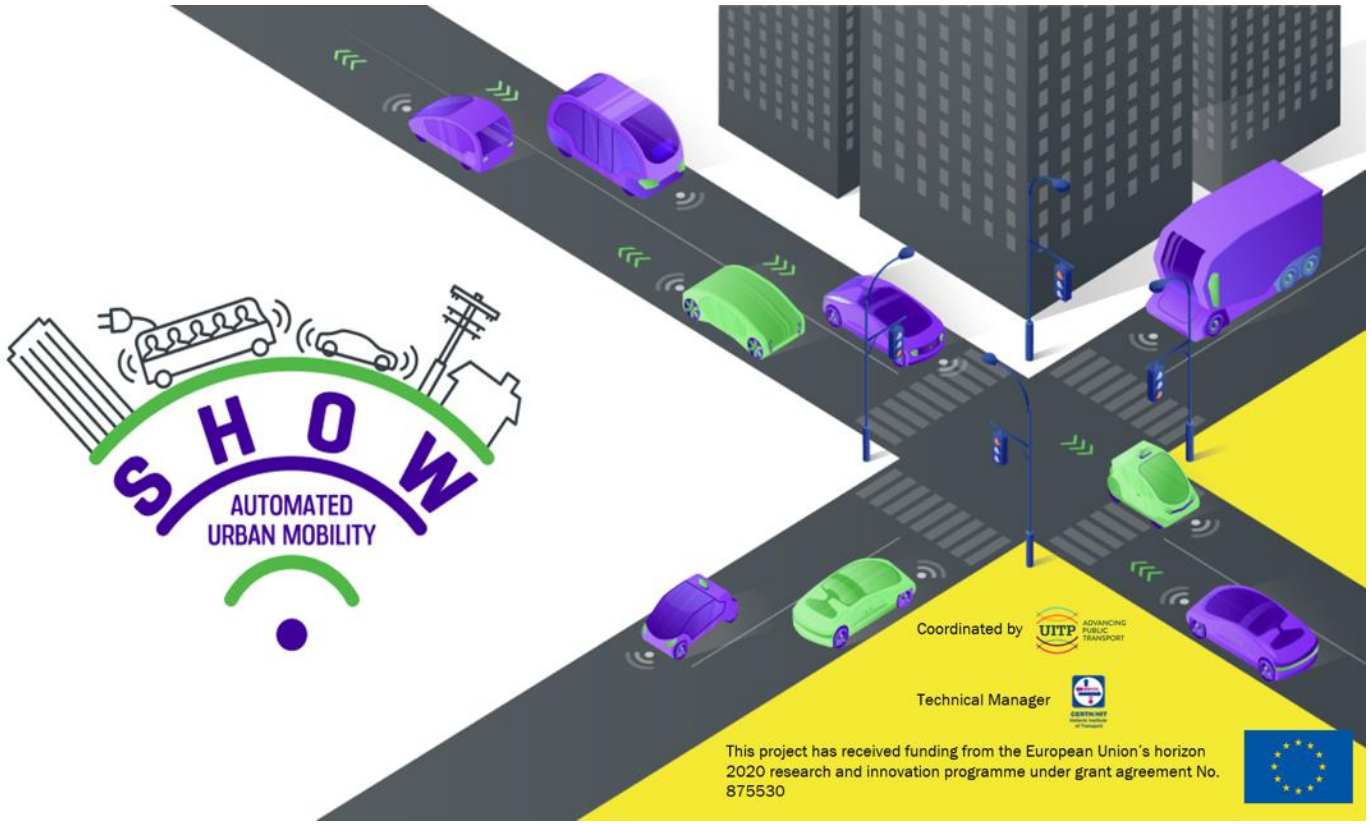
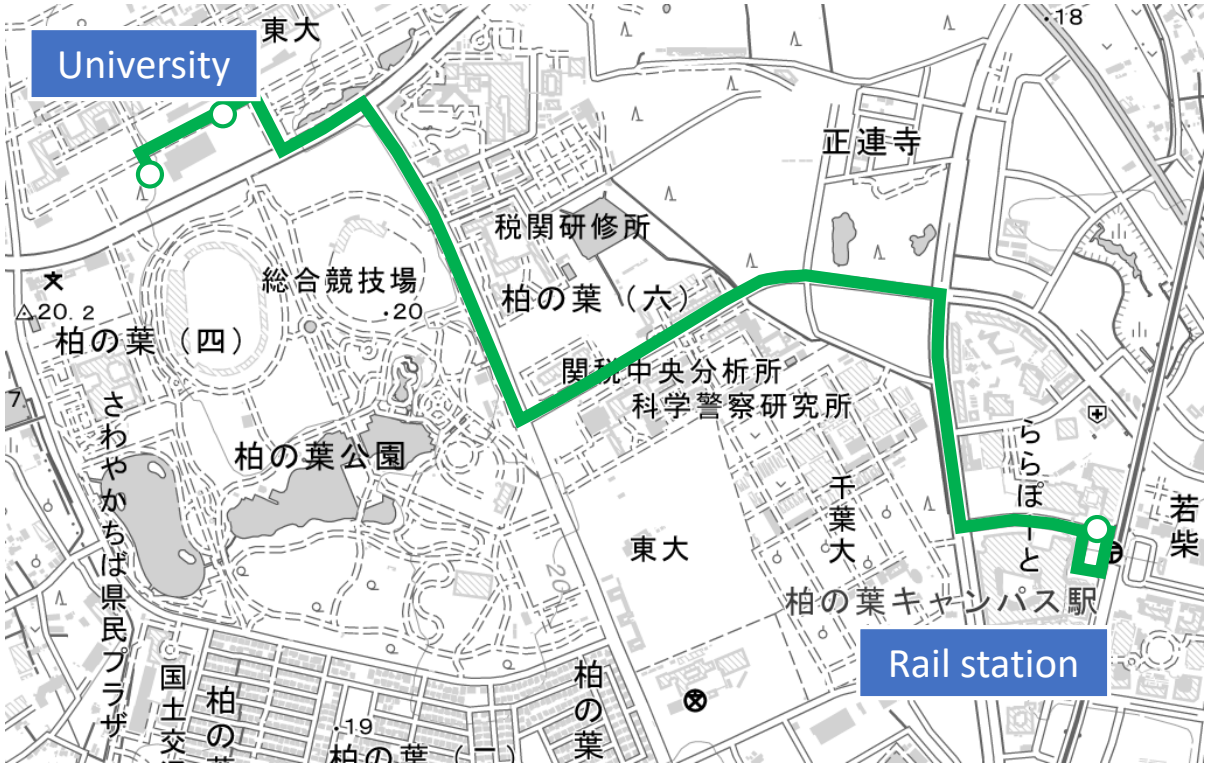
International Collaboration
- Collaboration with SHOW project in Europe -

- NDA was concluded between SHOW and ITS Japan/Univ. of Tokyo.
- Discussion has been started for future collaborations.

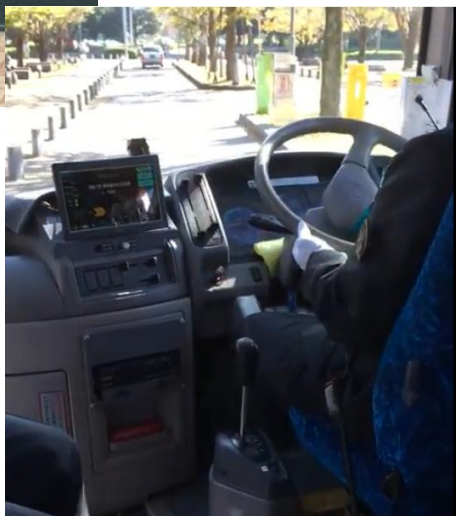


Long Term Automated Bus Pilot Deployment (Kashiwa-city)

- Long term deployment since 1st Nov. 2019



※Source : Chiriin Map (Denshikokudo Web)



Connect between rail station and university by Automated Bus

Connected-ITS pilot project (Hiroshima-city)

Test vehicle & Test route

◆Tram : 4 vehicles

760MHz ・GNSS

Vehicle onboard unit

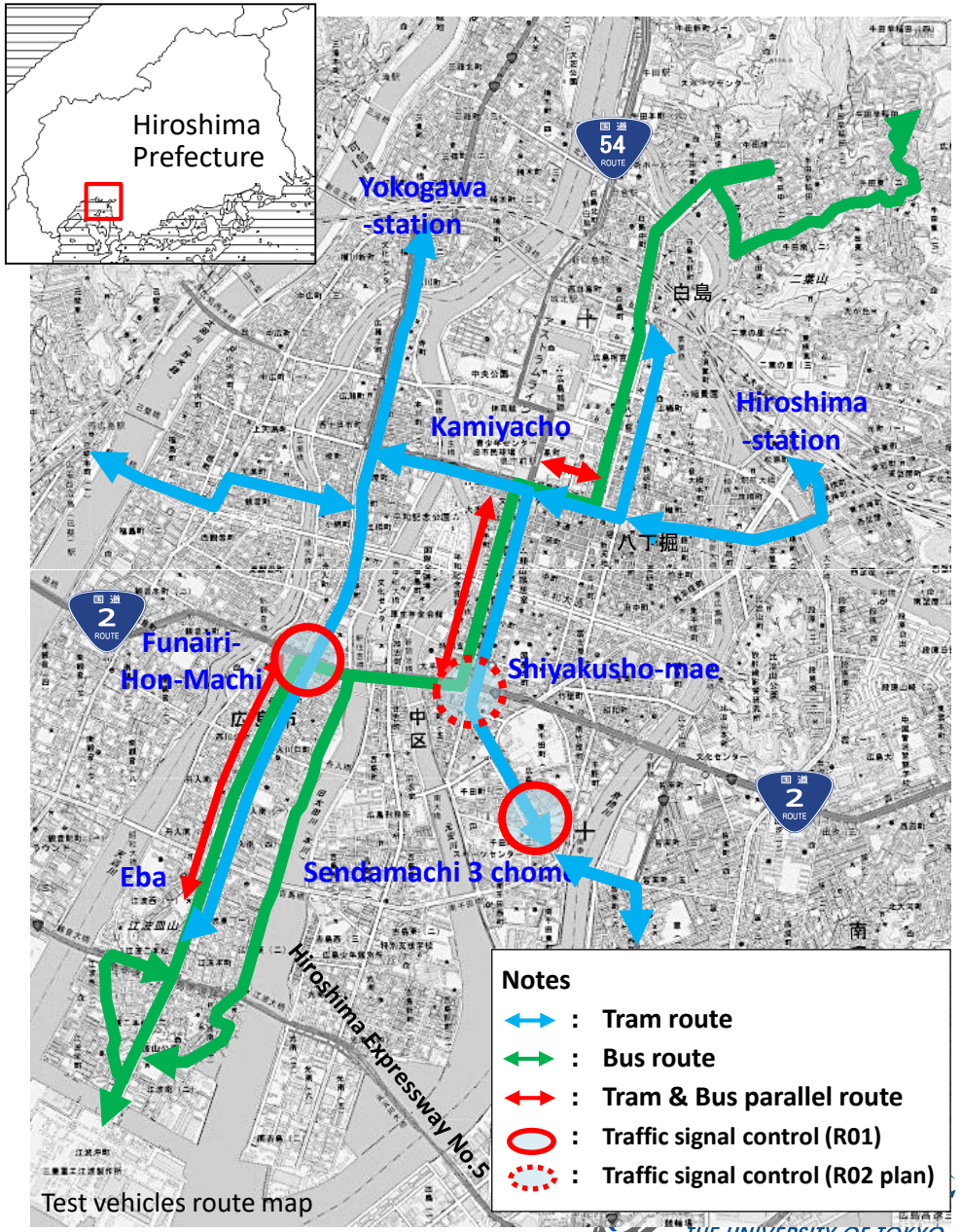
Support monitor(HMI)

◆Transit Bus : 3 vehicles

760MHz ・GNSS

Vehicle onboard unit

Support monitor(HMI)



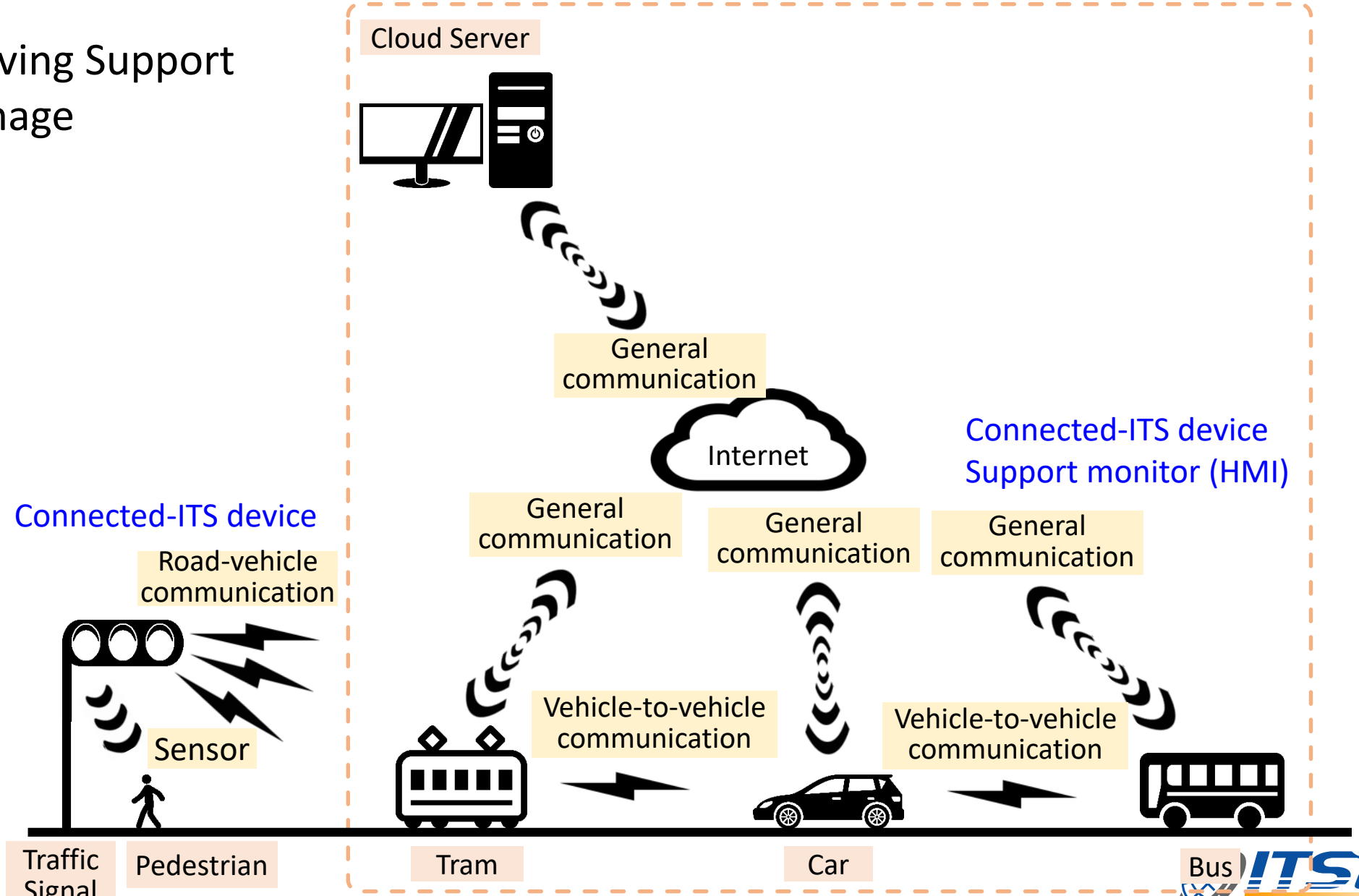
Test vehicles route map

※Source : Public transport priority type Smart city planning project by connected-ITS (Oct. 2020)

※Source : Chiriin Map (Denshikokudo Web)

Connected-ITS pilot project (Hiroshima-city)

Safety Driving Support
System Image



※Source : Public transport priority type Smart city planning project by connected-ITS (Oct. 2020)

Sustainable Mobility* Framework by exploiting automated driving technologies

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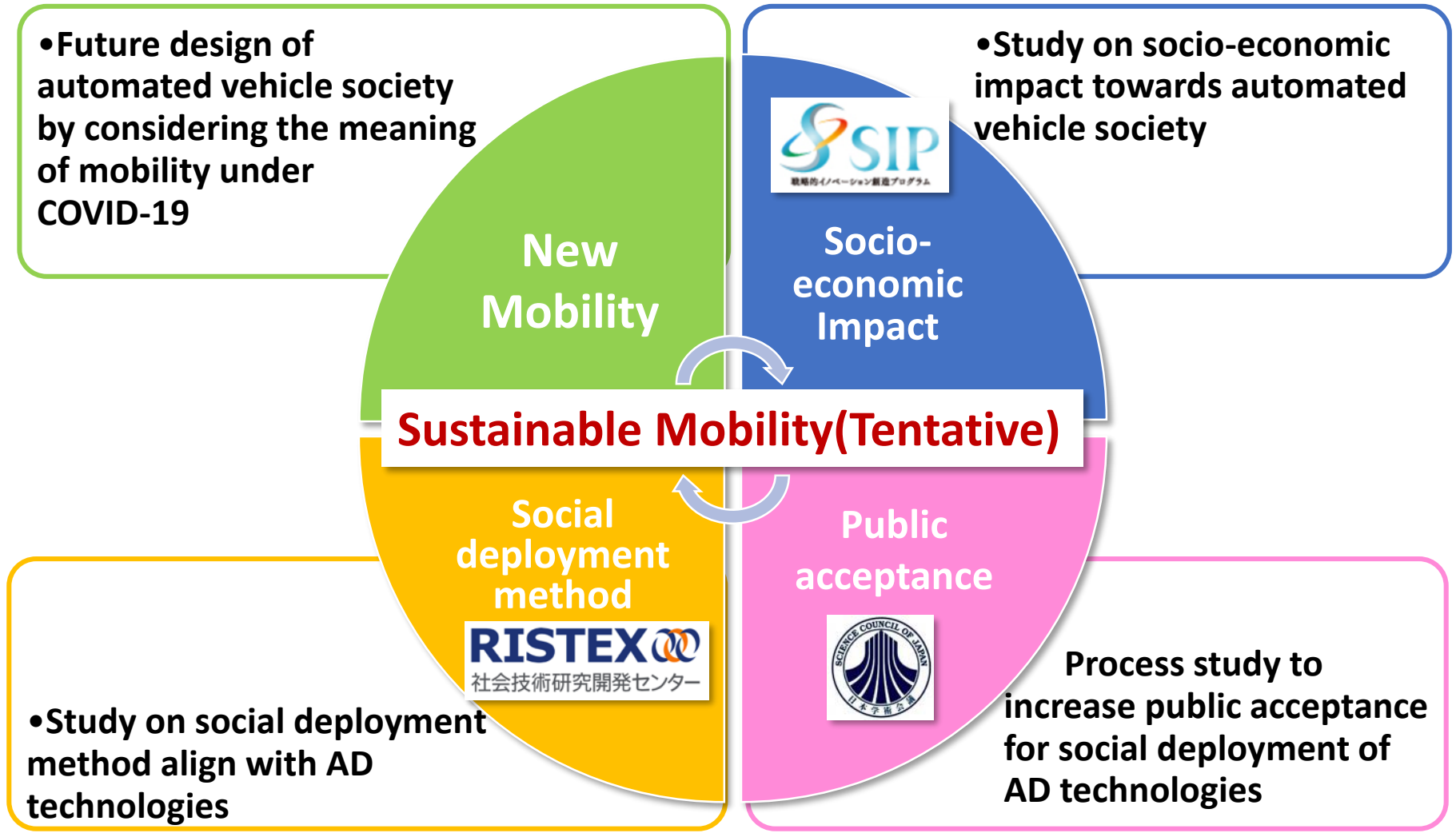

Mobility Vision for Post COVID-19

Suggestion

- Address demand-flattening and utilize a surplus by demand-flattening.
- Further involvement by public authority for public transport business.
- Realize integrated mobility service by technology development and implementation of new mobility service and MaaS.
- Technology development and system design to contribute effective logistics and productivity improvement.
- Correspond to still-existing mobility demands.

Big wave of society change triggered by infection measures may be a good opportunity to proceed solving these issues, although some of issues cannot be implemented in the past.

Concluding Remarks

- UTmobI and Mobility Innovation Liaison Meeting were established to enhance academia networking to challenge future Mobility Innovation.
- Mobility Innovation Liaison Meeting is promoting activities for Sustainable Mobility.
- Establishment of eco-system is important for sustainable automated vehicle operation.
- Pilot deployments in Kashiwa-city and Hiroshima-city are in progress.