

Research and Development of SIP Part.1

FOTs in Tokyo waterfront area

FOTs for cooperative automated driving systems are testing under actual traffic environments with 29 participants from diverse sectors in Japan and other countries.



Tokyo Waterfront City area (general road)

- Signal display and change timing information via ITS infrastructure
- HD 3D map linked with signal info. etc.

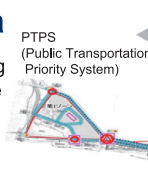


ITS infrastructure at over 30 point



Haneda airport area

- Signal display and change timing information via ITS infrastructure
- Magnetic marker
- Bus stop, designated lane for Bus service



Precise Docking to the platform



Dedicated bus lane

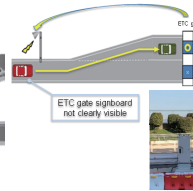
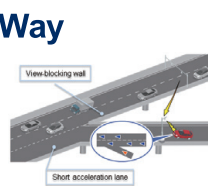
Participants



Period: Oct.2019 – Mar. 2021

Metropolitan Express Way

- Merging assistance on the main lane of highways
- ETC gate open/close info.
- Lane level traffic flow regulation info. etc.



Roadside sensor

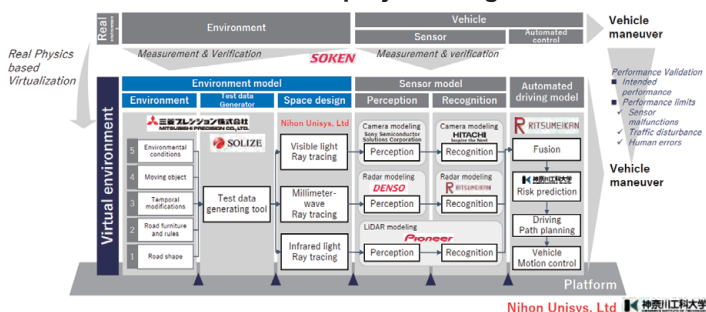


Safety assurance in virtual space

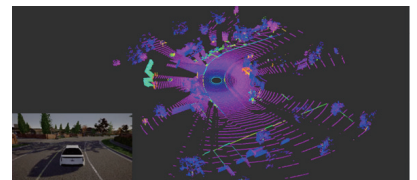
Developing Virtual Simulation contributes to Automated driving Safety assurance validation methodology

DIVP® (Driving Intelligence Validation Platform)

DIVP® project design



LiDAR simulation



Odaiba Virtual Community-ground



- Highly consistent sensor modeling
- Sensing domain based approach
- Open Interfaces