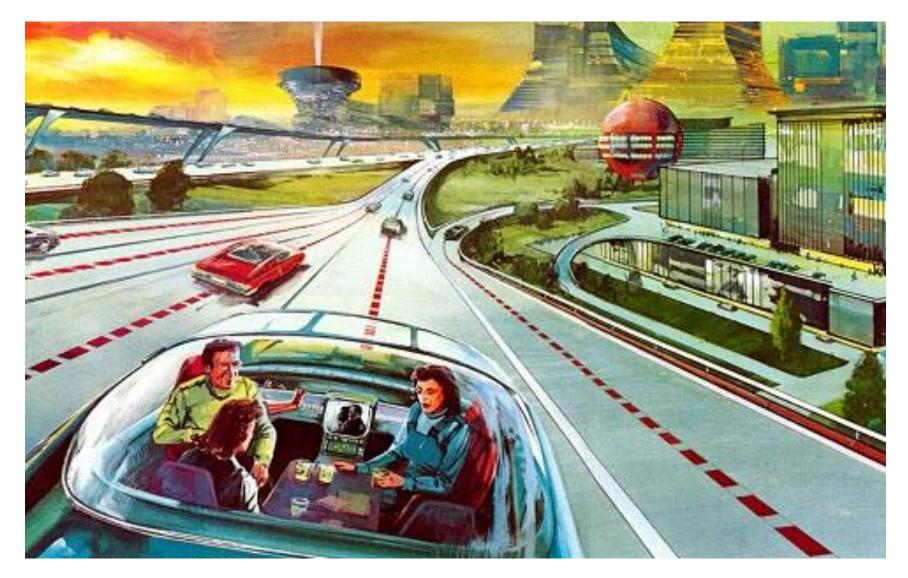
A DMP Group Company

Chris Thibodeau CEO & President

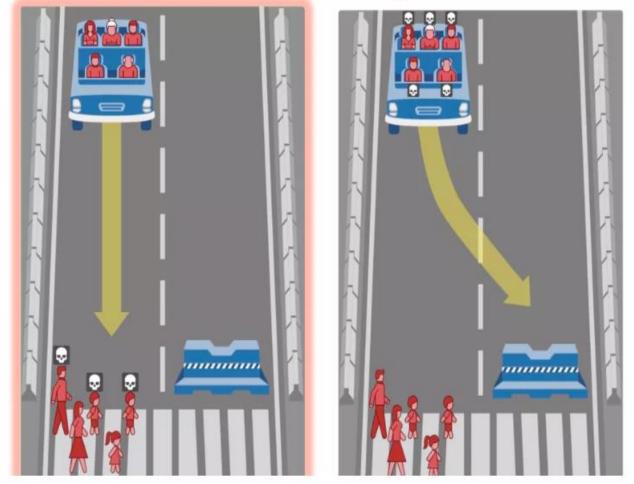
What Is your Vision of the Future?





Common Autonomous Vehicle Assumptions

- Self driving cars are a long ways off
- Self driving cars will reduce traffic jams
- Self driving cars will produce less air pollution
- Eventually we will all have self driving cars
- The biggest issue with self driving cars is "SAFETY"

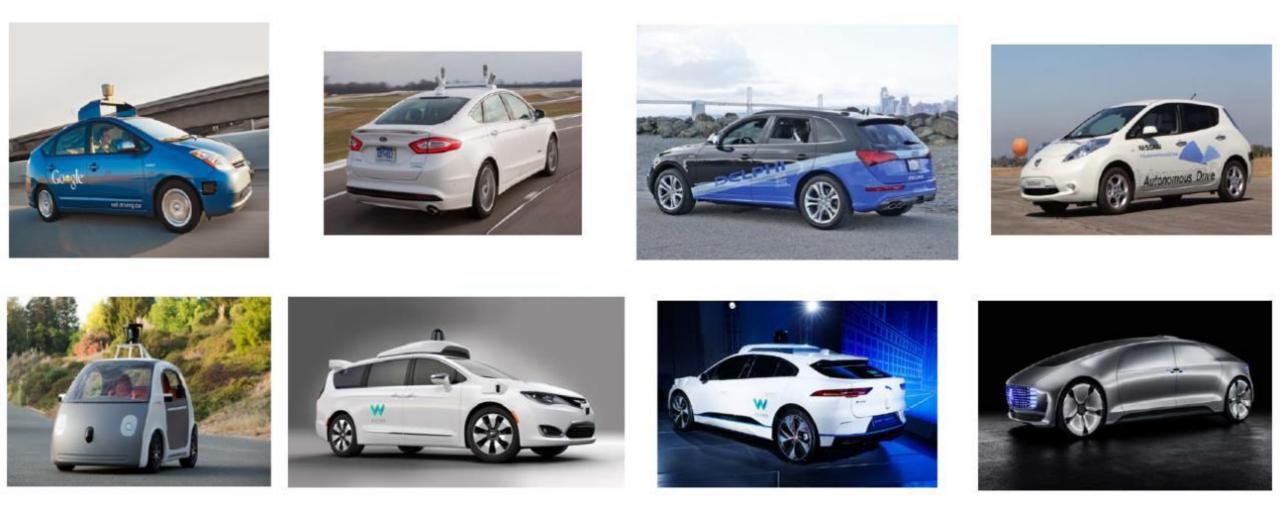


What should the self-driving car do?

A sample scenario from the Moral Machine: should the user hit the pedestrians or crash into the barrier? Source: The Verge Oct. 24, 2018



What Is your Vision of the Future of Autonomous Driving?





What Is your Vision of the Future of Autonomous Driving?





The Future of Autonomous Driving





Autonomous Driving Benefits

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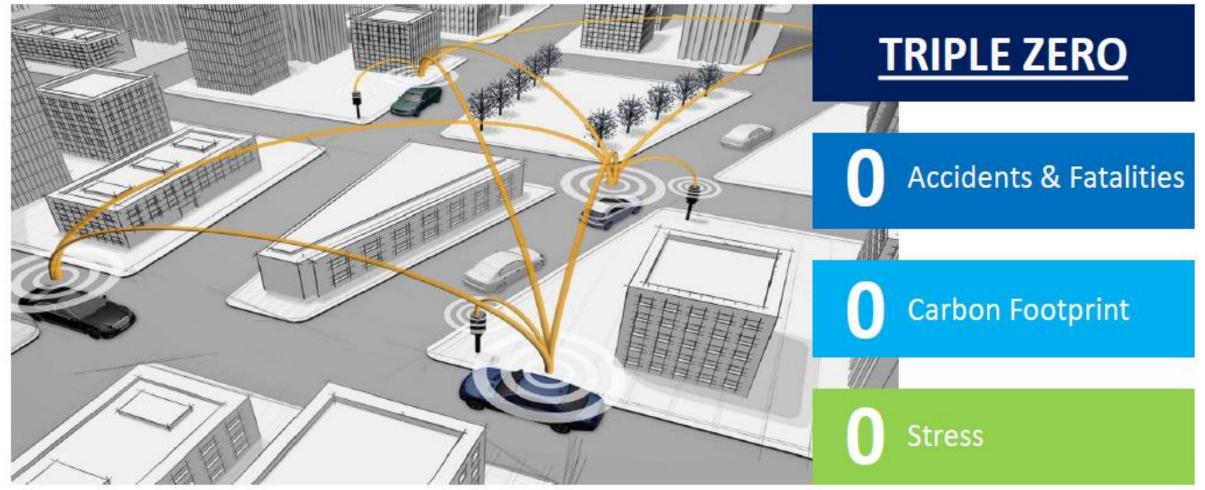
10000

Autonomous Driving Will Create Benefits Beyond Auto Sales

Wide Ranging Benefits Will Support Broad Based Market Acceptance



Smart Mobility: The Movement of People and Goods with....



Source: CAK SAE OCTODER



Self-driving Vehicles Will Depend On SMART Cities....



...The Deployment Of Technology And Data To Improve People's Lives

- V2V & V2I Communication
- Autonomous
 Navigation & Collision
 Avoidance
- Location Based Services
- Smart & Resilient Infrastructure



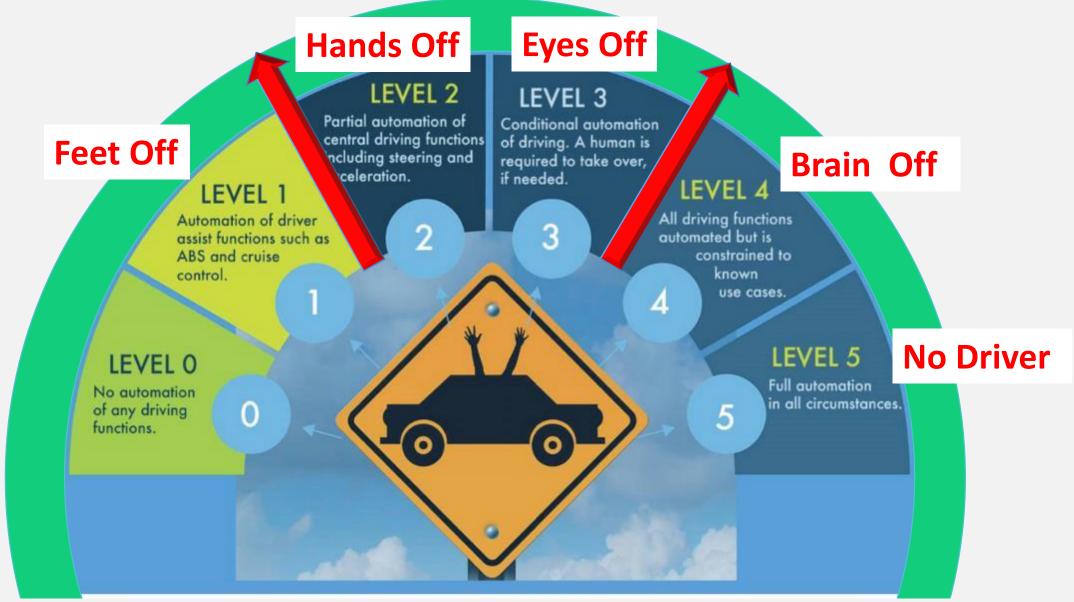
Autonomous System Architecture

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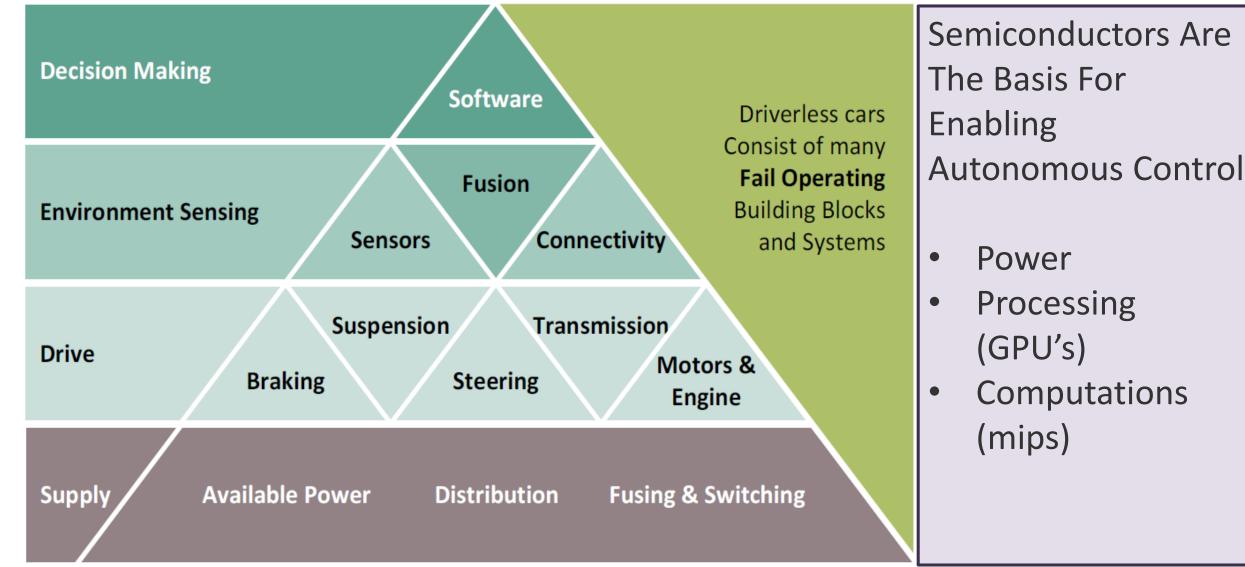
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Self-driving Market Segments Have Unique Requirements



Building Blocks for Autonomous Driving.....





Ushr – HD Maps Digital Transformation

Mapping the world for autonomous Vehicles.

Creating The Most Accurate & Comprehensive HD Maps.

Autonomous Vehicle Value Proposition

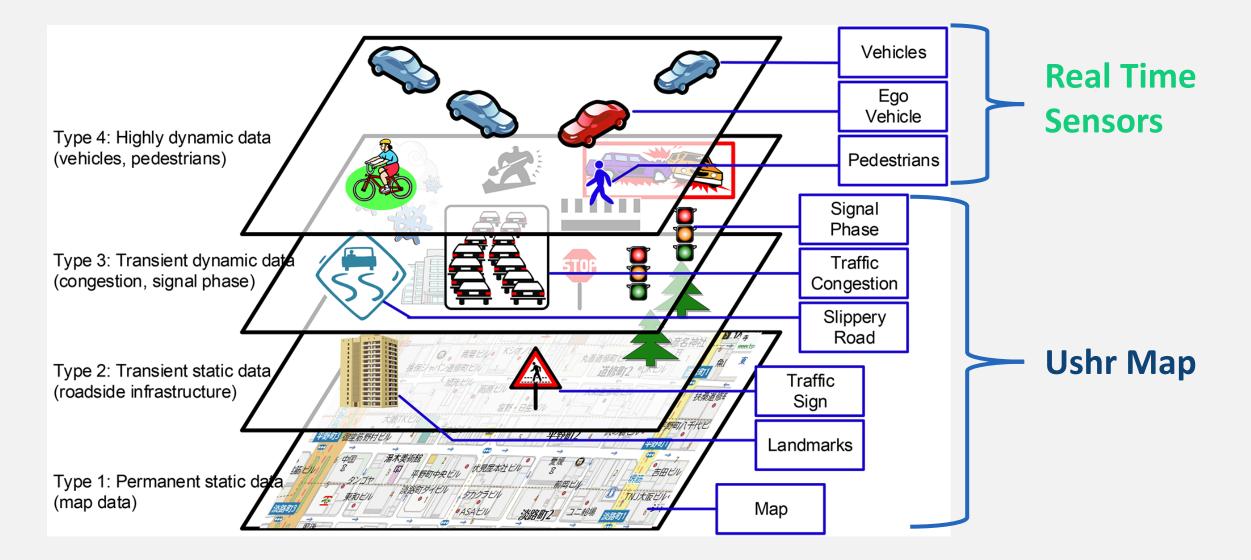


- Must Drive Better Than Humans
- Sensor Fusion Is Essential
- Map = Longest Range Sensor
- Allows Vehicles To "See" The Road Ahead
 - **Pavement Markings**
 - **Geometric Data**
 - **Road Objects**
 - **Derived Data**
- Applies To All Level Of Autonomous Vehicles

Sensors + Software + Memory (Map) = Knowledge



Ushr – HD Maps More Info Than Just Roads



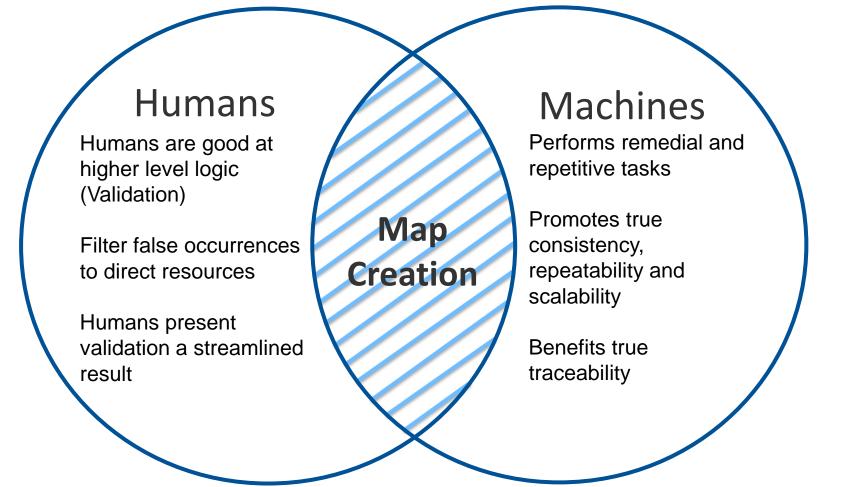
Key Steps to Ensure Quality

Safety & Performance Requirement				
Define feature requirement based on use cases and safety cases Define severity based on FMEA	Highly Accurate LiDAR Base Map			\ \
	Use precision survey procedures to process LiDAR Validate accuracy randomly sampled independent survey points		es Precisely from Lidar	
		Automatically extract feature positions directly from LiDAR Include controls to ensure quality	Automatically and manually attribute feature type Include controls to ensure quality	Validate Quality Preform automatic testing Validate with random sampling





Delicate Balance Between Humans And Machines



The Balance for Optimal Map Creation Comes from The Strengths of Humans and Machines Producing A Mixture of Algorithm Sets (infused with Deep Learning)

Ushr Is The Dominant HD Mapping And Software Provider For Autonomous Driving Systems



"We are what we repeatedly do. Excellence, then, is not an act, but a habit." Aristotle