

SIP-adus Workshop 2017 (Human Factors)

SIP Human Factors Research Project

Task C

Study of Communication between Automated Vehicle and Other Road Users

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Main topics of the 3-year studies in Task C

- Year 1 (FY2016) In-vehicle and fixed-point observations, in-field experiment – To study non-verbal communication between drivers and other road users
- Year 2 (FY2017) In-field (test truck) experiment
 - To investigate the effect of external HMIs (messages, lamp, etc.) and ID display (ex. in automated driving) on behavior of surrounding road users.
- Year 3 (FY2018) In-field (test truck) experiment
 - To identify fundamental requirements for external HMIs and ID display for sending messages to surrounding road users (prototyping included).

Communications in driving situation

 Communication between drivers (D2D), between drivers and pedestrian (D2P)



Yielding to other road users



Vehicle motion, lighting device



Hand gestures, eye contact

Safety and security, smooth traffic flow

Drivers take various types of communication method when yielding to other road users

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Purpose of the study in FY2016

Research question

How do drivers behave to yield to other road users (pedestrians, drivers)?

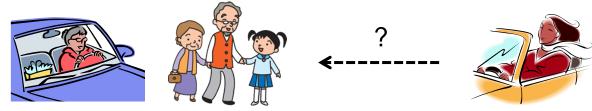
- How do drivers behave for pedestrians or drivers?





Vehicle behavior, headlight operation, (decelerating, stopping) (headlight flashing) hand gesture, etc.

- How do pedestrians or drivers judge such driver/vehicle behavior?



Experiment methods

Communication behaviors between driver and pedestrians (D2P) were observed at fixed-points and also in the car driven the participant.

□ Fixed-point observation 【Qualitative】



Local road; unsignalized crosswalk (D2P) etc.

□ Web survey 【Qualitative】



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Cultural effects on communication Effect of driving license on communication □ In-vehicle observation 【Quantitative】





Local road; unsignalized crosswalk (D2P) etc.

□ In-field experiments [More quantitative]





Pedestrians' judgement on driver yielding behavior (D2P).

Experiment car

- Measuring equipment
 - Laser range finder

Distance between surrounding road users

- 360-degree camera
 Surrounding road users' behavior
- In-vehicle cameras
 Driver behavior, etc.
- CAN data

Vehicle status, etc.

– GPS data

Vehicle position, velocity, etc.



Monitor for recording data

360-degree camera

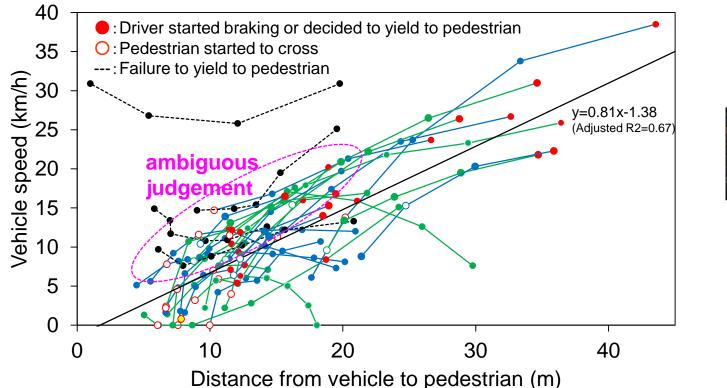


Laser range finder (Total 360-degree)

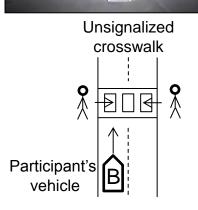


Center console

D2P on local roads (in-vehicle observation)



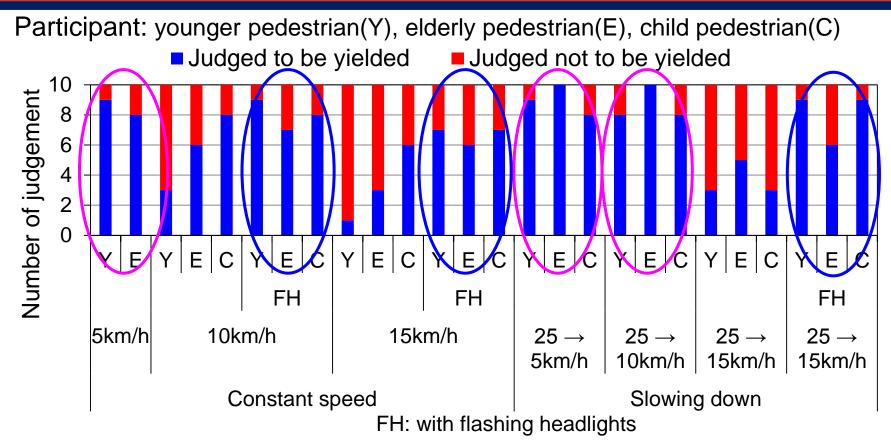




- Pedestrians started crossing when Car B slowed down to 0-15km/h with the distance 5-15m.
- Miscommunication occurred when Car B did not slow down enough for pedestrians to cross.

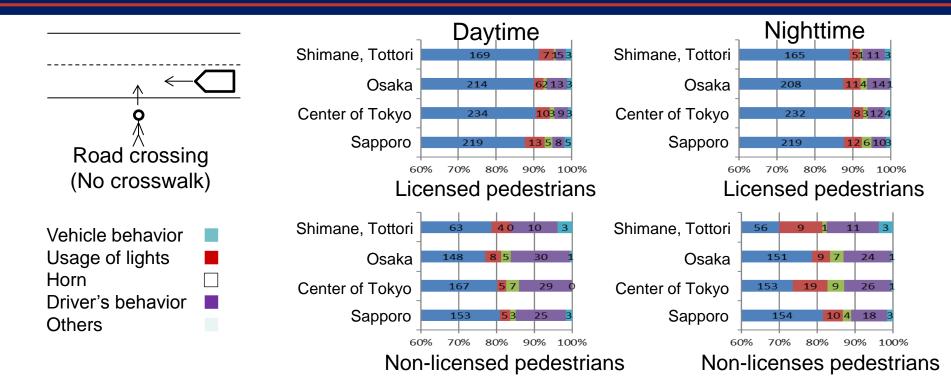
Cues for communication to pedestrians

D2P in local roads (In-field experiment)



- Pedestrians judged the approaching vehicle yielded to them when the vehicle approached at very low speed (5km/h) and large deceleration.
- Flashing headlights gave an additional signal to yield, resulting in more judgement, both for the constant speed and slowing down conditions.

D2P in local roads (Web survey)



- The effects of type of pedestrian (licensed or non-licensed) were larger than the effects of location (culture) in Japan.
- Non-licensed pedestrians relied less on vehicle behavior and more on driver's behavior in comparison to licensed pedestrians.
- The effects of time of day were larger among the non-licensed pedestrians with more reliance on usage of lights in nighttime.

Summary and future works

- Summary
 - Vehicle motion/behavior was found to be the primary communication signal when yielding to pedestrians.
 - Flashing headlights gave an additional signal to yield, resulting in more judgement to be yielded for pedestrians.
 - Some profiles of vehicle behavior caused miscommunications. An external HMI for automated vehicles is expected to reduce occurrence of such miscommunications.
 - Communication signals for pedestrians to judge that approaching car yields to them were different between licensed and non-licensed pedestrians.
- Future works
 - The effect of external HMIs (messages, lamp, etc.) and ID display on recognition and behavior of surrounding road users.

Thank you for your attention.

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